

SEASONAL TIME SERIES

I. SEASONAL MA(q)

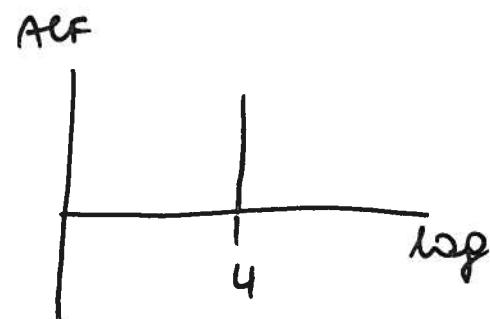
$$Z_t = \Theta_q(B^s)a_t$$

where $\Theta_q = 1 - \theta_1 B^s - \theta_2 B^{2s} - \dots - \theta_q B^{qs}$

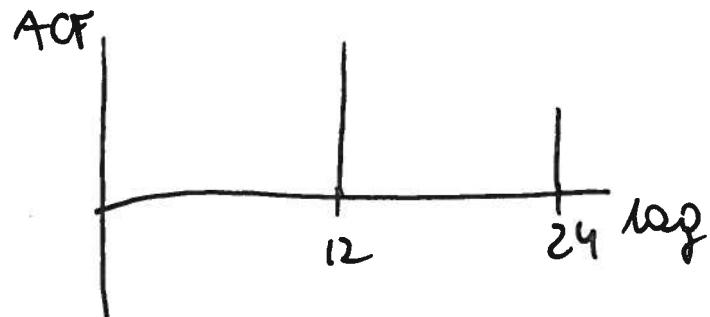
and $s=12$ for monthly patterns, or $s=4$ for quarterly

$$Z_t = a_t - \theta_1 a_{t-s} - \theta_2 a_{t-2s} - \dots - \theta_q a_{t-qs}$$

Ex: $MA(1)_4 : Z_t = a_t - \theta_1 a_{t-4}$



Ex: $MA(2)_{12} : Z_t = a_t - \theta_1 a_{t-12} - \theta_2 a_{t-24}$



AUTOCORRELATIONS $\rho_s, \rho_{2s}, \dots, \rho_{qs} \neq 0$ AND
CUT OFF AT LAG q's

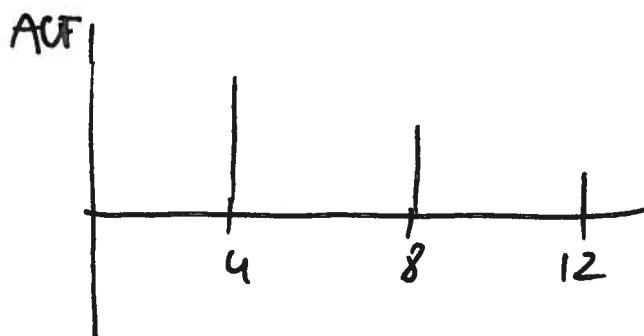
2. SEASONAL AR(p):

$$\Phi_p(B^s) Z_t = a_t$$

where $\Phi_p = 1 - \phi_1 B^s - \phi_2 B^{2s} - \dots - \phi_p B^{ps}$

$$Z_t = \phi_1 Z_{t-s} + \phi_2 Z_{t-2s} + \dots + \phi_p Z_{t-ps} + a_t$$

ex: $AR(1)_u$: $Z_t = \phi_1 Z_{t-4} + a_t$



AUTOCORRELATIONS $\rho_{js} = \phi_j^s$ AND DIE OUT EXPONENTIALLY.
ALL OTHER autocorrelations are 0.

- IF YOU OBSERVE THAT THE AUTOCORRELATIONS AT SEASONAL LAGS DIE OUT VERY SLOWLY, AT A LINEAR RATE, TRANSFORM Z_t into $(1-B^s) Z_t = Z_t - Z_{t-s}$

- IF THE DATA DISPLAY BOTH TREND AND AUTOCORRELATION AT SEASONAL LAGS THAT DIE OUT AT A LINEAR RATE TRANSFORM z_t INTO $(1-B)(1-B^s)z_t \Rightarrow \Delta \Delta_s z_t$

$$z_t: \quad \Delta z_t \quad (1-B^s) \Delta z_t \quad (\text{ex } s=4)$$

z_1	Δz_1	\dots
z_2	$\Delta z_2 = z_2 - z_1$	\dots
z_3	$\Delta z_3 = z_3 - z_2$	\dots
z_4	$\Delta z_4 = z_4 - z_3$	\dots
z_5	$\Delta z_5 = z_5 - z_4$	\dots
z_6	$\Delta z_6 = z_6 - z_5$	$\Delta z_6 - \Delta z_2$
z_7	$\Delta z_7 = z_7 - z_6$	$\Delta z_7 - \Delta z_3$
z_8	$\Delta z_8 = z_8 - z_7$	$\Delta z_8 - \Delta z_4$

SEASONALITY IS A PREDICTABLE PATTERN THAT NEEDS TO BE REMOVED, OR INCLUDED IN THE MODEL:

$$\Phi_{P_1}(B^s) \cdot \Phi_{P_2}(B) z_t = \Theta_{Q_1}(B^s) \Theta_{Q_2}(B) a_t$$

IF THAT IS TOO DIFFICULT, USE DESSEASONALIZED DATA OR APPLY FILTER XII (RATS, SAS)

INTEGRATED ARIMA (p,q)

- IS CALLED ARIMA(p,d,q) WHERE d IS THE ORDER OF INTEGRATION.

$$(1-B)^d \Phi_p(B) z_t = \Theta_q(B) a_t$$

IT IS A NONSTATIONARY PROCESS. IN MOST CASES d=1, AND THE PROCESS IS "INTEGRATED OF ORDER ONE". THAT PROCESS NEEDS TO BE TRANSFORMED INTO FIRST DIFFERENCES PRIOR TO THE MODELLING:

$$(1-B) z_t = \Delta z_t = z_t - z_{t-1}$$

Next, we can estimate:

$$\Phi_p(B) \Delta z_t = \Theta_q(B) a_t$$

USING THE STANDARD METHODS:

- THE AUTOREGRESSIVE PROCESS, INTEGRATED OF ORDER 1 IS CALLED THE RANDOM WALK:

$$z_t = z_{t-1} + a_t$$

ITS FIRST DIFFERENCE $\Delta z_t = a_t$ IS STATIONARY